610 Final review: Classical Electrodynamics

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Gauss's theorem:

$$\oint \vec{E} \cdot \vec{S} = 4\pi kQ = \frac{Q}{\epsilon_0}$$
$$\nabla \cdot \vec{E} = -\nabla^2 \phi = \frac{\rho}{\epsilon_0}$$
$$\oint \vec{E} \cdot d\vec{l} = 0$$

Uniqueness of solution to Poisson's equation:

If we impose Dirichlet or Neumann boundary conditions, the solution is unique.

- Dirichlet boundary condition: the value of ϕ is specified on the boundary
 - Neumann boundary condition: $\nabla \phi \cdot \hat{n}$ is specified on the boundary

Electrostatic Energy:

$$W = \frac{1}{2} \int d^3x \ \rho(\vec{x})\phi(\vec{x}) = \frac{1}{2} \epsilon_0 \int d^3x \ |\vec{E}|^2$$

 $\frac{1}{2}\epsilon_0 |\vec{E}|^2$ can be identified as the energy density stored in electrostatic field.

Force on a conducting surface:

• Energy charge from a virtual displacement, the force per unit area is

$$f = \frac{F}{\Delta A} = -\frac{\Delta W/\Delta x}{\Delta A} = \frac{\alpha^2}{2\epsilon_0}$$

where α is the charge area density on the surface.

• Directly from electronic field, the force per unit area is

$$f = \frac{F}{\Delta A} = \frac{(\alpha \Delta A) \dot{E}_{external}}{\Delta A} = \frac{\alpha^2}{2\epsilon_0}$$

Usage of Green function:

We need to generalize the Green function method to address more general boundary conditions, where either ϕ or $\vec{E} \cdot \hat{n}$ are specified on the boundaries.

* If $\phi(\vec{x})$ satisfies <u>Dirichlet boundary conditions</u>, the value of ϕ is specified at boundary, choose $G_D(\vec{x'}, \vec{x}) = 0$ for all $\vec{x'}$ on the surface S to get

$$\phi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int_V \rho(\vec{x}') G_D(\vec{x}', \vec{x}) \, d^3 \vec{x}' - \frac{1}{4\pi} \oint_S \phi(\vec{x}') (\nabla' G_D(\vec{x}', \vec{x}) \cdot \hat{n}') \, ds'$$

* For <u>Neumann boundary conditions</u>, $\nabla \phi \cdot \hat{n}$ is specified on the boundary. The situation is more complicated, because we cannot choose $\nabla' G_N(\vec{x'}, \vec{x}) \cdot \hat{n'} = 0$ for all $\vec{x'}$ on the surface *S*. This choice is inconsistent because

$$\oint_{S} \nabla' G_{N}(\vec{x}', \vec{x}) \cdot \hat{n}' \, ds' = \int_{V} \nabla'^{2} G_{N}(\vec{x}', \vec{x}) \, d^{3}\vec{x} = \int_{V} -4\pi\delta^{3}(\vec{x}' - \vec{x}) \, d^{3}\vec{x} = -4\pi$$

The simplest consistent choice is

$$\nabla' G_N(\vec{x}', \vec{x}) \cdot \hat{n}' = -\frac{4\pi}{S}$$
, where S is the area of the surface

for all $\vec{x'}$ on the surface *S*. The solution is

$$\phi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int_V \rho(\vec{x}') G(\vec{x}', \vec{x}) \, d^3 \vec{x}' + \frac{1}{4\pi} \oint_S \left[G(\vec{x}', \vec{x}) (\nabla' \phi(\vec{x}') \cdot \hat{n}') \right] ds' + \langle \phi \rangle_S$$

where $\langle \phi \rangle_S$ is the average value of ϕ over whole surface. If one of the surface is at infinity, $\langle \phi \rangle_S$ is typically vanishes. Under the Neumann boundary condition, we have $G_N(\vec{x'}, \vec{x}) = G_N(\vec{x}, \vec{x'})$.

Laplace operator:

• In rectangular coordinate

$$\nabla^2 V = \frac{\partial^2}{\partial x^2} V + \frac{\partial^2}{\partial y^2} V + \frac{\partial^2}{\partial z^2} V = 0$$

general solution:

$$V(x, y, z) = \sum_{n,m=1}^{\infty} A_{nm} \sin(\alpha_n x) \sin(\beta_n y) \sinh(\gamma_{nm} z)$$
$$= \frac{m\pi}{2} \text{ and } \gamma_{nm} = \pi \sqrt{\frac{n^2}{2} + \frac{m^2}{2}}.$$

where $\alpha_n = \frac{n\pi}{a}$, $\beta_m = \frac{m\pi}{b}$ and $\gamma_{nm} = \pi \sqrt{\frac{\pi}{a^2} + \frac{\pi}{b^2}}$

• In spherical coordinate

$$\nabla^2 V = \frac{1}{r^2} \left[\frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) \right] + \frac{1}{r^2 \sin \theta} \cdot \frac{\partial}{\partial \theta} \left(\sin \theta \cdot \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} = 0$$

general solution:

$$V(r, \theta, \phi) = \sum_{l=0}^{+l} \sum_{m=-l}^{+l} \left(A_{lm} r^{l} + B_{lm} r^{-(l+1)} \right) Y_{lm}(\theta, \phi)$$

general solution with azimuthal symmetry m = 0:

$$V(r,\theta) = \sum_{l=0}^{\infty} \left(A_l r^l + B_l r^{-(l+1)} \right) P_l(\cos \theta)$$
$$P_l(x) = \frac{1}{2^l l!} \frac{d^l}{dx^l} \left(x^2 - 1 \right)^l$$
$$\frac{d}{dx} (P_{l+1} - P_{l-1}) = 2(l+1) P_l$$
$$Y_{lm}(\theta,\phi) = \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\cos \theta) e^{im\phi}$$

• In cylindrical coordinates

$$\nabla^2 V = \frac{1}{\rho} \left[\frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) \right] + \frac{1}{\rho^2} \left(\frac{\partial^2 V}{\partial \phi^2} \right) + \frac{\partial^2 V}{\partial z^2} = 0$$

• In 2-D

$$\nabla^2 V = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial V}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 V}{\partial \phi^2} = 0$$

general solution

$$V(\rho, \phi) = R(\rho)\Psi(\phi)$$

$$R(\rho) = a\rho^{\nu} + b\rho^{-\nu}$$

$$\Psi(\phi) = A\cos(\nu\phi) + B\sin(\nu\phi)$$

general solution for full azimuthal range:

$$V(\rho,\phi) = a_0 + b_0 \ln \rho + \sum_{n=1}^{\infty} a_n \rho^n \sin(n\phi + \alpha_n) + \sum_{n=1}^{\infty} b_n \rho^{-n} \sin(n\phi + \beta_n)$$

general solution for $\phi \in [0, \beta]$ with $V(\phi = 0) = V(\phi = \beta)$:

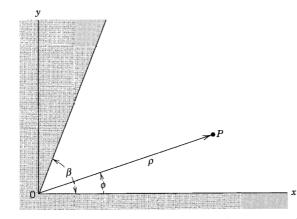


Figure 2.12 Intersection of two conducting planes defining a corner in two dimensions with opening angle β .

$$V(\rho,\phi) = V(\phi=0) + \sum_{m=1}^{\infty} \left(a_m \rho^{m\pi/\beta} + b_m \rho^{-m\pi/\beta} \right) \sin(m\pi\phi/\beta)$$

Orthogonality relation:

$$\int_{0}^{2\pi} \sin(n\phi) \cdot \sin(m\phi) \, d\phi = \int_{0}^{2\pi} \cos(n\phi) \cdot \cos(m\phi) \, d\phi = \pi \delta_{m,n}$$
$$\int_{0}^{2\pi} \sin(n\phi) \cdot \cos(m\phi) \, d\phi = 0$$
$$\int_{-1}^{1} dx \, P_{l}(x) P_{m}(x) = \frac{2}{2l+1} \delta_{lm}$$

Useful expansion:

$$\frac{1}{|\vec{x} - \vec{x'}|} = \sum_{l=0}^{\infty} \frac{r_{<}^{l}}{r_{>}^{l+1}} P_{l}(\cos \gamma)$$

where $r_{<}$ and $r_{>}$ are smaller one and larger one between $|\vec{x}|$ and $|\vec{x}'|$, γ is the angle between \vec{x} and $\vec{x'}$.

$$\frac{1}{|\vec{x} - \vec{x'}|} = 4\pi \sum_{l=0}^{\infty} \sum_{m=-l}^{l} \frac{1}{2l+1} \frac{r_{<}^{l}}{r_{>}^{l+1}} Y_{lm}^{*}(\theta', \phi') Y_{lm}(\theta, \phi)$$

$$P_{0}(x) = 1$$

$$P_{1}(x) = x$$

$$P_{2}(x) = \frac{1}{2}(3x^{2} - 1)$$

$$P_{3}(x) = \frac{1}{2}(5x^{3} - 3x)$$

$$P_{4}(x) = \frac{1}{8}(35x^{4} - 30x^{2} + 3)$$